

COPS Aircraft Flight Planning:

Mission Scenario

“High Pressure Convection”

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CI forcing processes

- ① ② Surface/boundary layer triggered air mass convection
(non-forced/non-frontal)
- ③ ④ Large-scale lifting, no surface front; convection breaking out
over a wider area (forced/non-frontal)
- ⑤ Embedded convection along a surface front in a region of
large-scale lifting (forced and frontal)

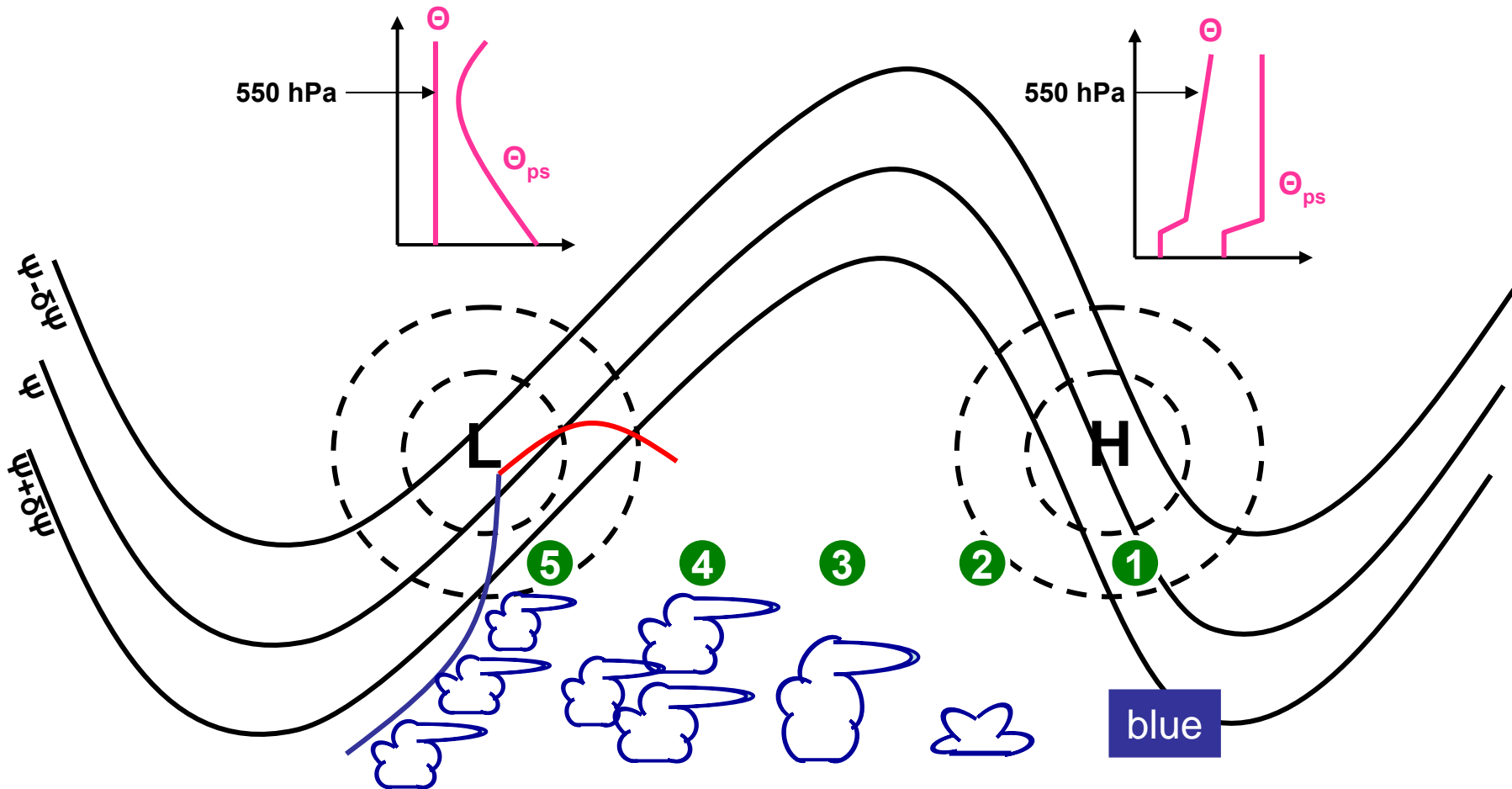
Mission Scenarios

Scenario “Forced Convection” addresses cases ③ to ⑤

Scenario “High Pressure Convection” addresses cases ① to ③

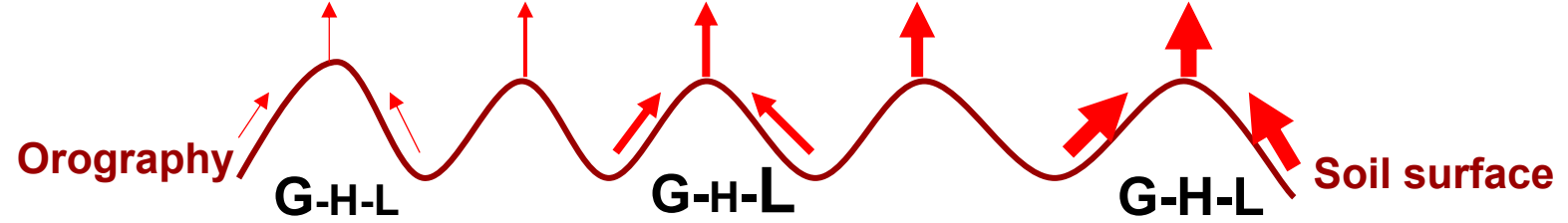
Scenario “Targeted Observations” (E-TReC)

500 hPa: **Trough** ← **PVA, WAA** **Lifting** → **Ridge** **NVA, CAA** **Subsidence** **Trough**



Flight pattern →

DeDe Org DeDe Area DeDe Indi Blue SupDe PreCon Blue



Mission Scenario “High Pressure Convection”

Blue Sky --- > Shallow Convection -- > Deep Convection-- > Dis. Convection

non frontal / non forced

07—08--09---10---11---12---13---14---15---16---17---18---19---20---21---22 local

G-Falcon -----FLUX pattern (up to 3 times)
-----FL 130 or 180 , Drops-----

F-Falcon -----MAP pattern (1) -----→BOX pattern CuCong, Cb-----
-----FL 150, Drops-----→FL150, Drops -----

(*)BAE 146-----LONG-LEGS---→BOX pattern-----
-----VFR < FL 100-→FL 100/270 -----

(*)DO 128-----FLUX pattern (2 to 3)-----→BOX pattern (DeDe)-----
-----mid/upper PBL (VFR)-----→up to FL 245 (IFR) -----

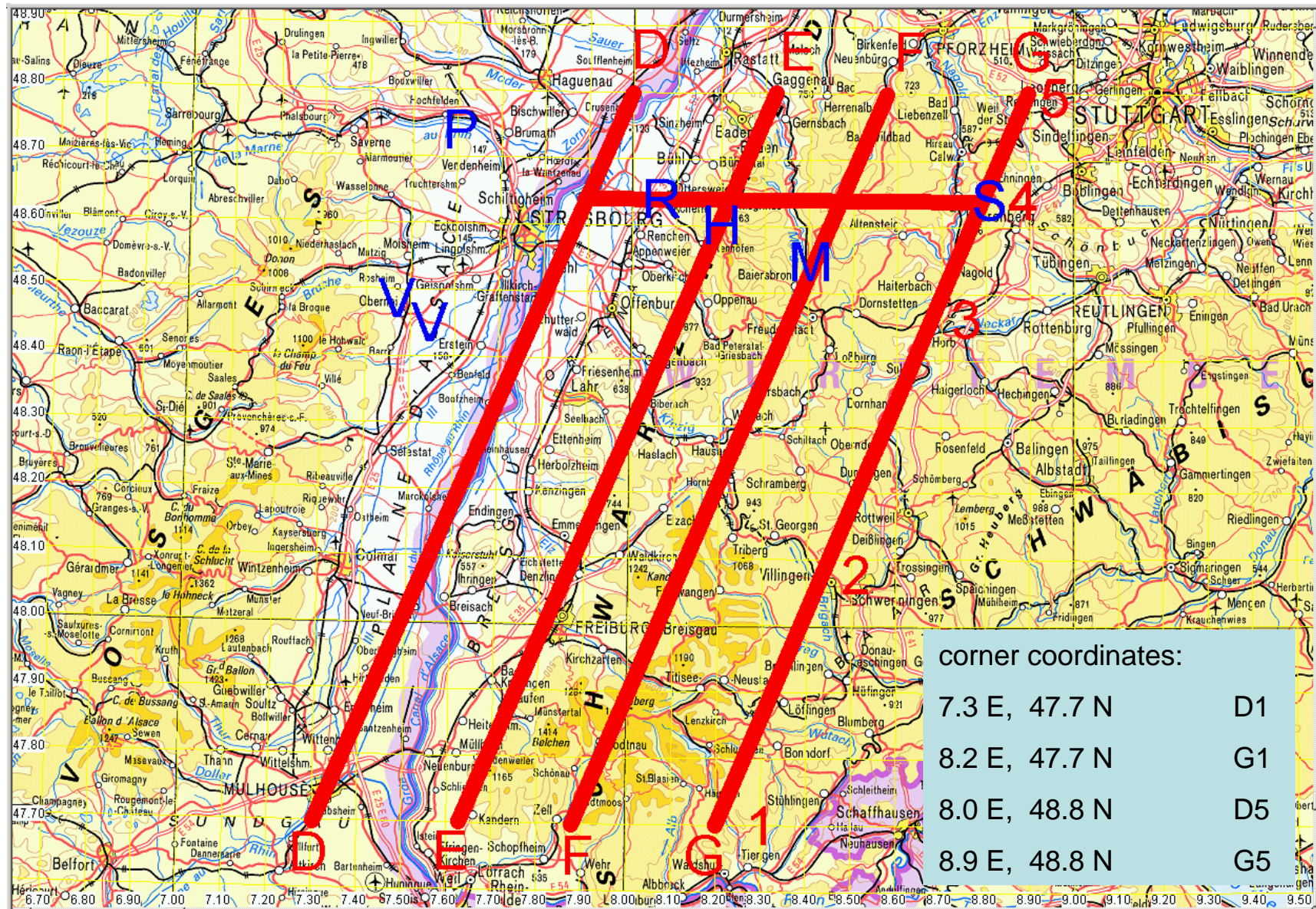
***Zeppelin**--Valley pattern (Rhine-Kinzig-Murg-Nagold)-----Valley pattern (R-K-M-N)--→CuCong----
---lowest level, VFR-----lowest level, VFR-----→on request-

***Dimona**-----MAP (2 MAPs) or Valley-----MAP (2 MAPs) or Valley-----
-----lowest level PBL (VFR)-----lowest level PBL (VFR)-----

***Enduro**-----Triangle/Cross-Section/Slope-----Triangle/Cross-Section/Slope-----
-----low PBL, FL100 (VFR)-----low PBL, FL100 (VFR)-----

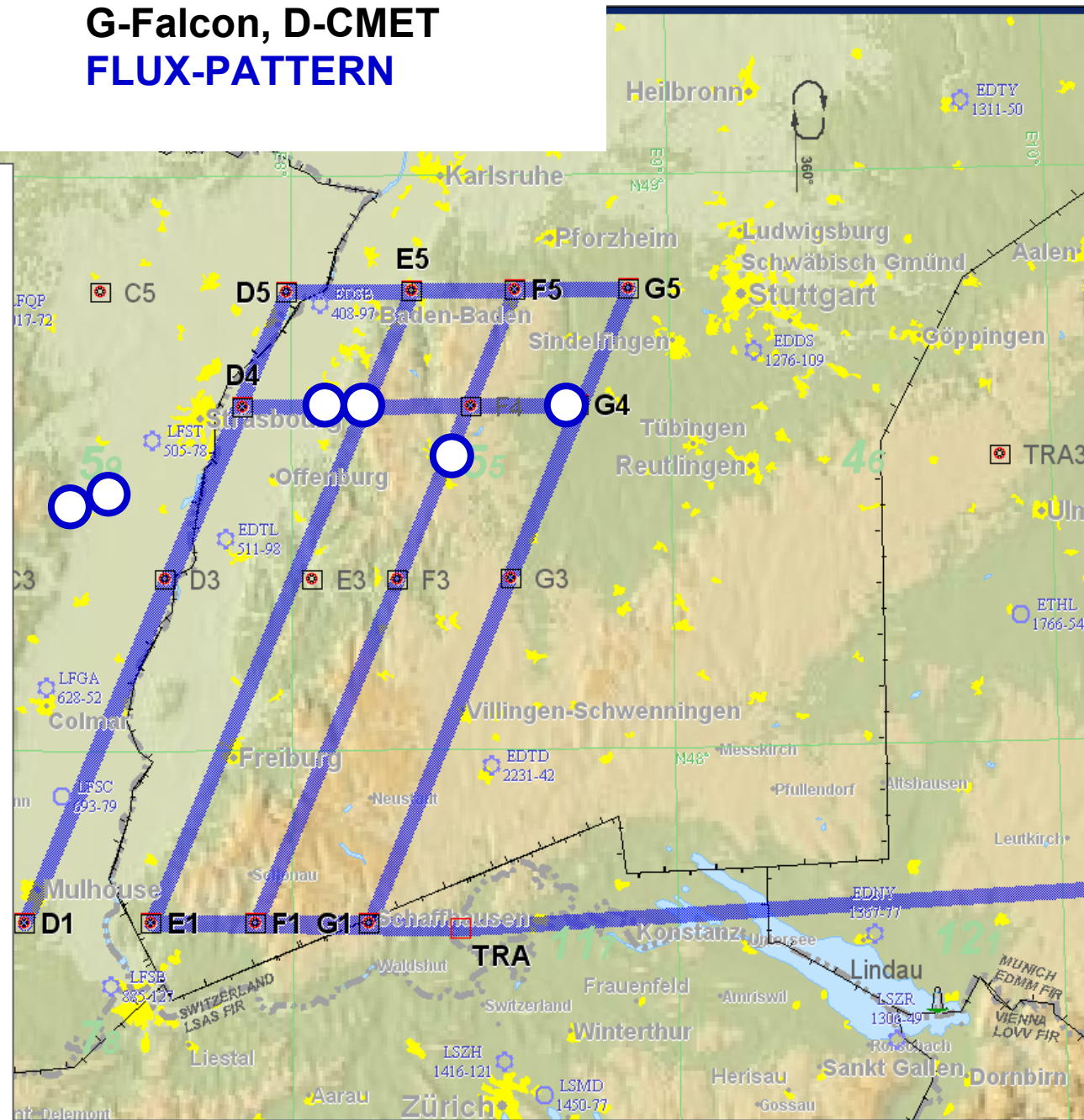
***: VFR**

Scenario: High Pressure Convection; Platform 2: G-Falcon; Mission: FLUX

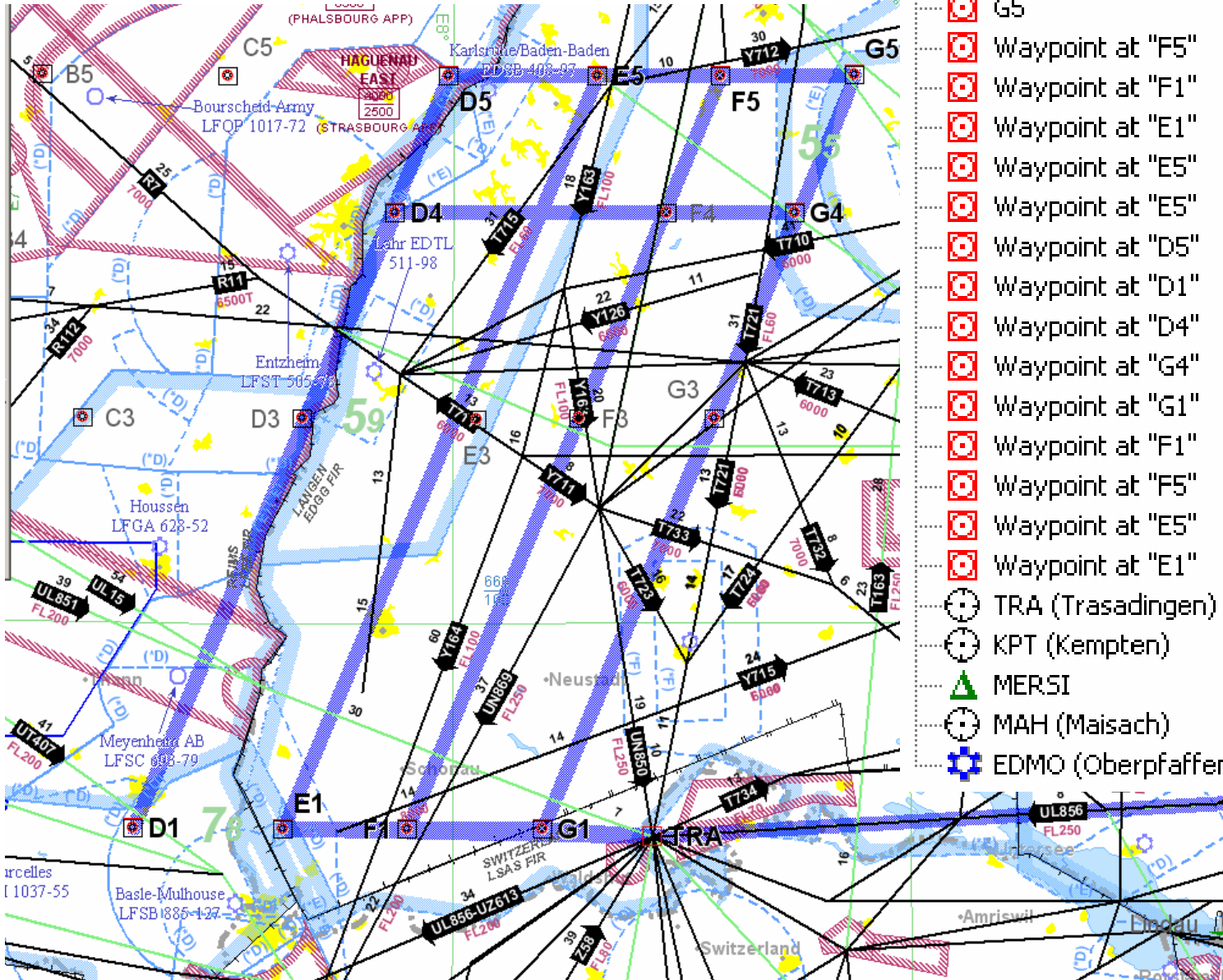


Scenario: High Pressure Convection
Platform 2: G-Falcon, D-CMET
Mission: FLUX-PATTERN

- # Flight level:
FL 180 (~ 6 km)
- # Pattern repetition:
max. 2 times
- # Dropsondes:
4 per flight
- # Coordination:
DO 128
F-Falcon
BAE146
- # 15-20 flight hours
(4-5 flights)
- # Remarks:
flight around noon;
cloud free conditions;
wind lidar in nadir mode.

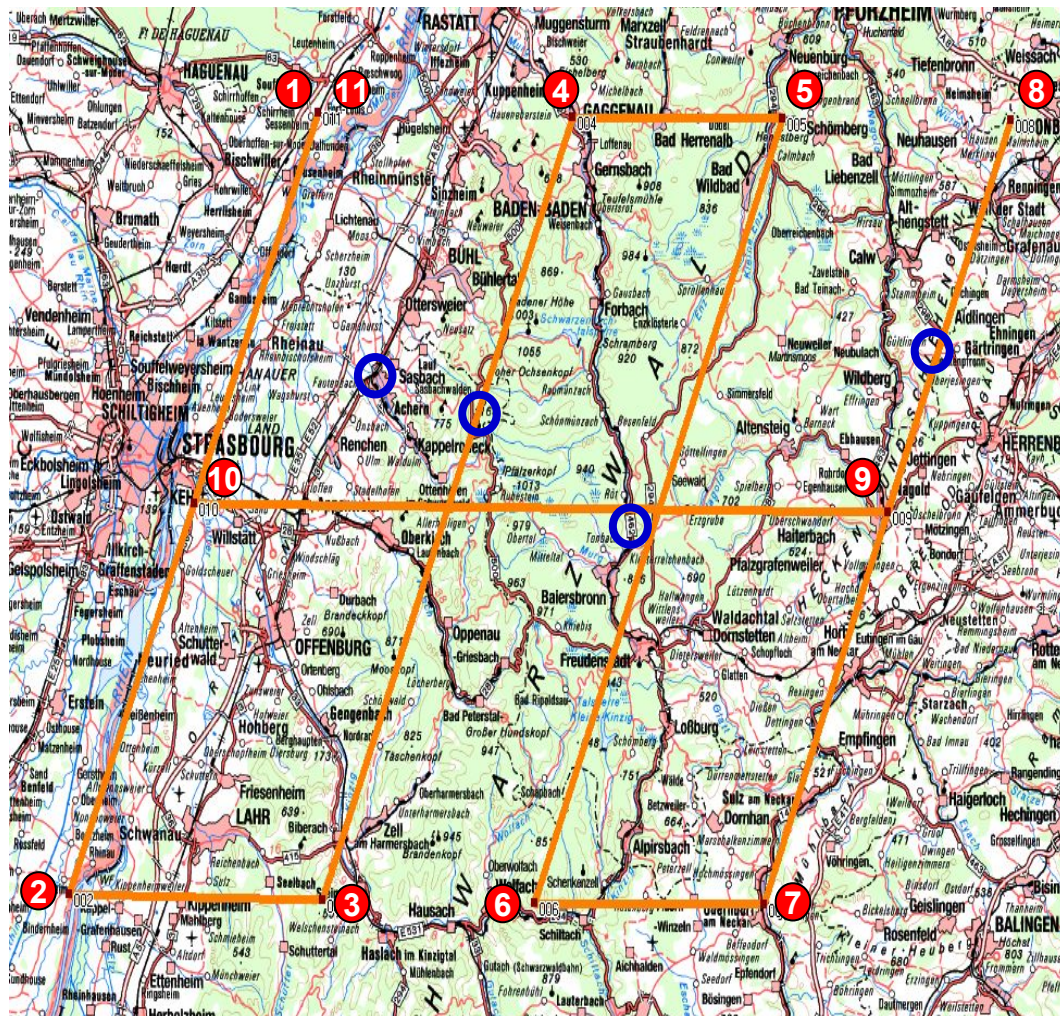


Scenario: High Pressure Convection
Platform 2: G-Falcon, D-CMET
Mission: FLUX-PATTERN



- EDMO (Oberpfaffenhof)
- KPT (Kempten)
- TRA (Trasadingen)
- Waypoint at "G1"
- G5
- Waypoint at "F5"
- Waypoint at "F1"
- Waypoint at "E1"
- Waypoint at "E5"
- Waypoint at "E5"
- Waypoint at "D5"
- Waypoint at "D1"
- Waypoint at "D4"
- Waypoint at "G4"
- Waypoint at "G1"
- Waypoint at "F1"
- Waypoint at "F5"
- Waypoint at "E5"
- Waypoint at "E1"
- TRA (Trasadingen)
- KPT (Kempten)
- MER.SI
- MAH (Maisach)
- EDMO (Oberpfaffenhof)

Scenario: High Pressure Convection
 Platform 5: DO 128, D-IBUF
 Mission: FLUXES-RHS



- # Upper level: below FL 100
- # Lower level: 500 ft agl
- # Coordination: D-CMET
BAE 146
Dimona
Enduro,
Zeppelin
- # Airbase: KA Baden/Baden
- # Level: 1-2 within PBL
1 above PBL
- # Profiles: on demand (< FL 100)
- # Specific: time-coordinated
flight with D-CMET
below northern
part of D-CMET

COPS Aircraft Flight Planning:

Mission Scenario

“Targeted Observations”

in sensitive upstream regions,
~ 24 h before deep convection within
COPS area is forecasted.

Scenario: Forced Convection
Platform 2: G-Falcon, D-CMET
Mission: TARGET

Red box: target region.

Black segment: sector of likely target regions with a radius of 1800 km.

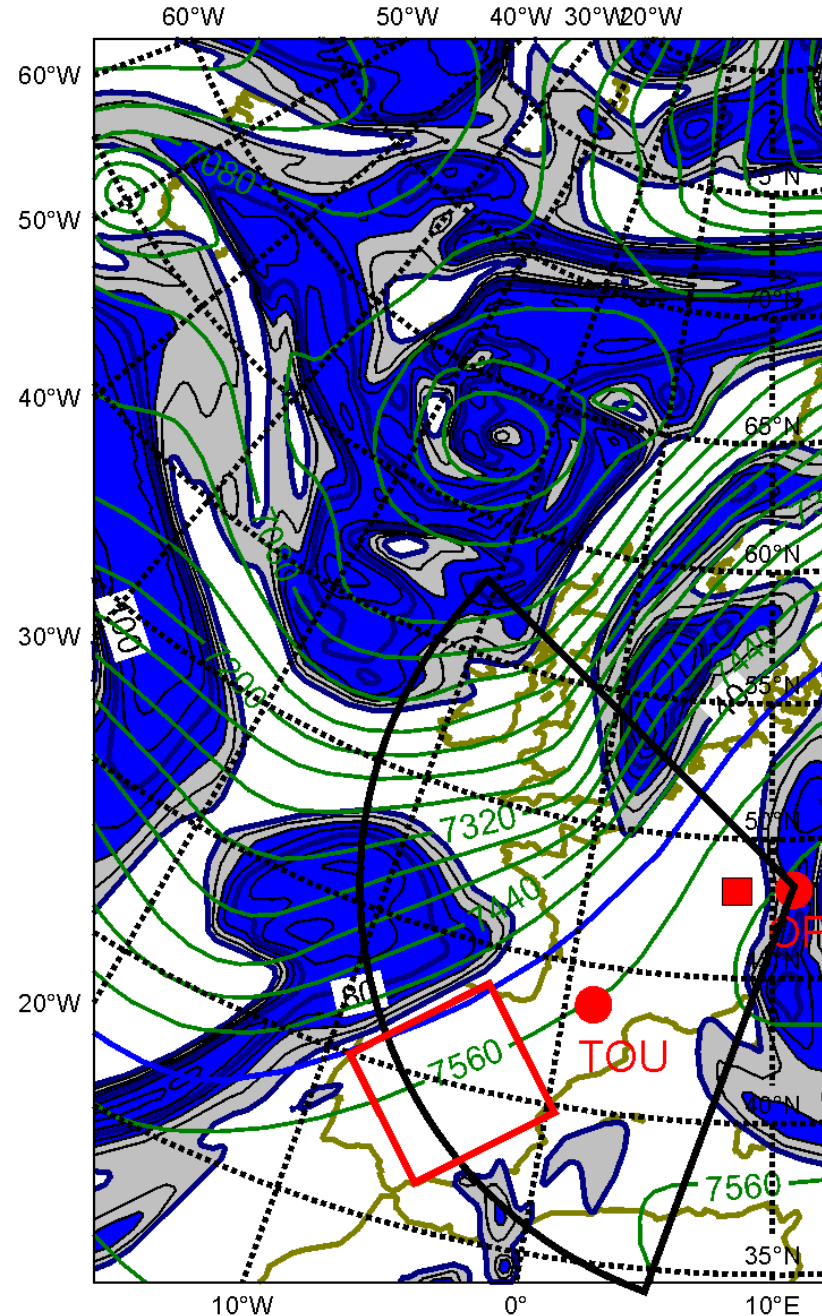
Measurements along PV streamers or streamlines during transfer to target region.

- Wind lidar in scanning mode
- FL 310 - 410
- ~20 flight hours (5 flights)
- ~30 dropsondes

Problem: DS over France/Spain/GB?

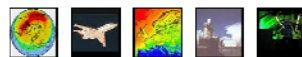
Relative humidity and geopotential height at 400 hPa on 18.6.02 12UT, 30 h before heavy precipitation occurred in the Black Forest.

ECMWF Analysis VT: Tuesday 18 June 2002 12UTC 400

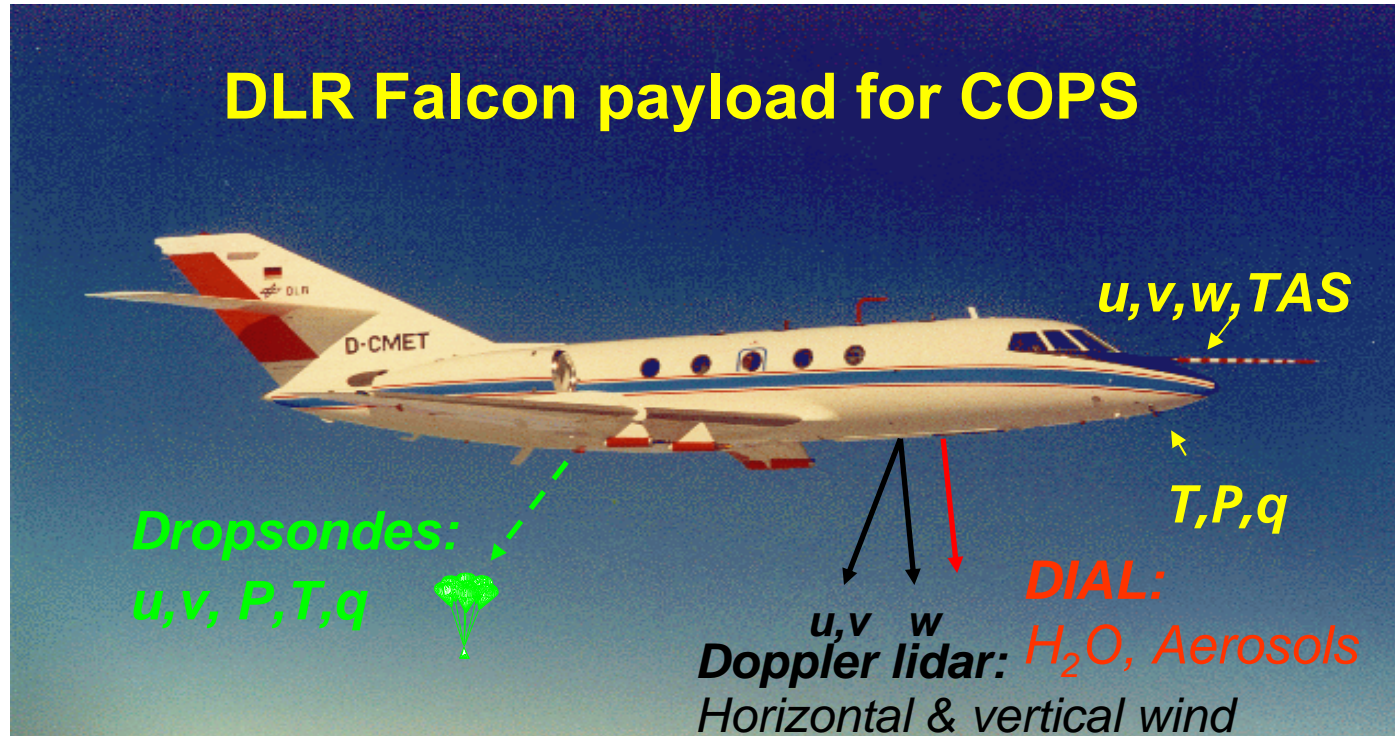


Proposed Decision Plan for Aircraft Missions

- **3 COPS generic mission scenarios:**
 - forced convection,
 - high pressure convection,
 - targeted observations.
- **COPS Briefings:**
 - All PI's can suggest missions based on the generic scenarios.
 - Decision making with respect to weather situation and remaining flight time allocated to the respective mission (like IHOP_2002).
 - **10:00 LT of day before mission: submit flight plan to ATC.**
Reasons: dense airspace over Germany, complex authorization process in France.



DLR Falcon payload for COPS



Altitude [m]	3000	6000	9500	12500
FL [hft]	100	200	310	410
Range [km]	2100	2800	3200	3700
Endurance [h]	04:10	04:15	04:45	05:00

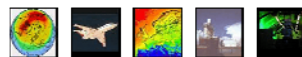
Availability: Weeks 26 - 31, 6 weeks from 28.6. - 5.8.2007.

installation, test & first mission flight in week 26.

In total 45 flight hours, 40 days funded 50/50 by DFG/DLR-IPA.

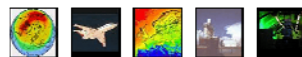


Institut für Physik
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Use Baden Airpark or Oberpfaffenhofen?

- **Advantages:**
 - **saves ~ 30 min for each flight,**
 - **more flexibility for weekend operations,**
 - **direct participation in mission planning & science meetings.**
- **Disadvantages:**
 - **no support for lidar maintenance,**
 - **limited data evaluation capability (no wind).**
- **Compromise:**
 - **occasionally land in Baden, depending on mission planning.**
 - **Permanently 2 DLR persons for mission planning in Baden during the 6 weeks of Falcon presence.**



DLR Falcon Objectives for COPS

Investigate the connection between tropospheric **wind and water vapour structures** (PV and moisture streamers, dry layers) and the location and timing of convection and precipitation. Detailed knowledge of the large-scale conditions is a prerequisite for improving QPF.

Characterise the initial and boundary conditions of convection with **high resolution wind and water vapour fields**. Investigate the spatial variability of humidity, wind and **latent heat fluxes**. Contribute to improve parameterisations of subgrid-scale processes over complex terrain.

Perform **targeted upstream measurements** for the quantification of **humidity advection** to the COPS area and for near real-time **assimilation** of humidity into a NWP model, which will significantly improve short range QPF.

